

## Smoothing-based inference with directional data

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EAFIT, September 15, 2017

# Directional data: what, why, where?

- ▶ Directional data are vectors whose support is the hypersphere

$$\Omega_q = \{ \mathbf{x} \in \mathbb{R}^{q+1} : \|\mathbf{x}\| = 1 \}$$

- ▶ Particular cases are the circle ( $q = 1$ ) and the sphere ( $q = 2$ )
- ▶ Statistical methods must account for the special nature of directional data
- ▶ Present in different applied fields: corner stone in bioinformatics, used in text mining

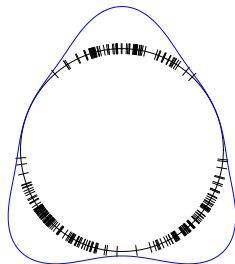


Figure: Circular density

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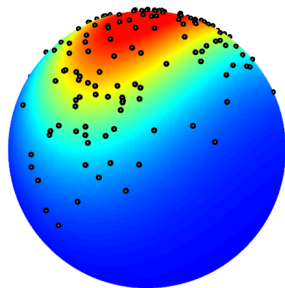


Figure: Spherical density

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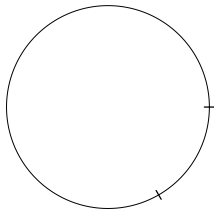


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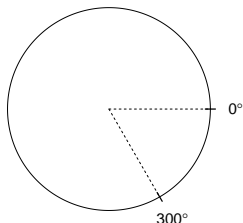


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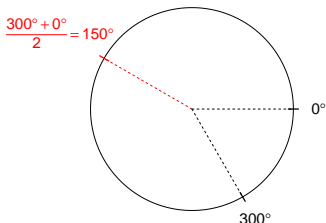


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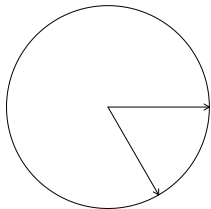


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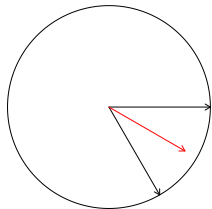


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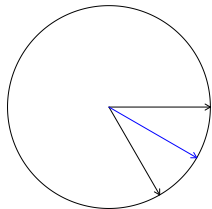












Figure: Circular mean

# Literature overview

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-  **Mardia, K. V. (1972).** *Statistics of Directional Data.* Academic Press.
-  **Batschelet, E. (1981).** *Circular Statistics in Biology.* Academic Press.
-  **Watson, G. S. (1983).** *Statistics on Spheres.* John Wiley & Sons.
-  **Fisher, N. I. (1993).** *Statistical Analysis of Circular Data.* Cambridge University Press.
-  **Fisher, N. I., Lewis, T. and Embleton, B. J. J. (1993).** *Statistical Analysis of Spherical Data.* Cambridge University Press.
-  **Mardia, K. V. and Jupp, P. E. (2000).** *Directional Statistics.* John Wiley & Sons.
-  **Hamelryck, T. and Mardia, K. V. and Ferkinghoff-Borg, J. (2012).** *Bayesian Methods in Structural Bioinformatics.* Springer.
-  **Pewsey, A., Neuhäuser, M. and Ruxton, G. D. (2013).** *Circular Statistics in R.* Oxford University Press.
-  **Ley, C. and Verdebout, T. (2017).** *Modern Directional Statistics.* Chapman and Hall/CRC.
-  **Ley, C. and Verdebout, T. (2018+).** *Applied Directional Statistics: Modern Methods and Case Studies.* Chapman and Hall/CRC.



# Protein structure modelling

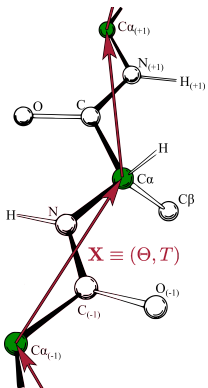


Figure: Backbone and  $C_{\alpha}$  representation

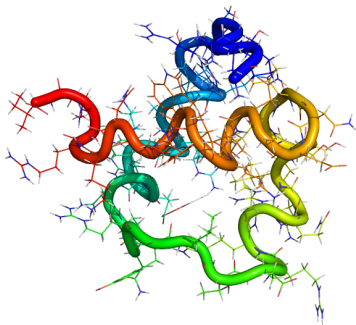


Figure: Cartoon view of a protein



Boomsma, W., Mardia, K. V., Taylor, C. C., Ferkinghoff-Borg, J., Krogh, A. and Hamelryck, T. A generative, probabilistic model of local protein structure. *PNAS*, 105(26):8932-8937



# Text mining

- ▶ Document  $d$  (Ronald Fisher, 1938):

“To call in the statistician after the experiment is done may be no more than asking him to perform a post-mortem examination: he may be able to say what the experiment died of.”

- ▶ Preprocessing of  $d$ :

- 1 Lowercase conversion, remove punctuation, remove format, ...
- 2 Pruning (remove stop words and too common or uncommon words)
- 3 Stemming (“statistician” → “statistic”)

- ▶ **Vector Space Model:**

- 1 Set a dictionary as a basis for a collection of documents:

$$D = \{\text{“hello”, “statistic”, “experi”, “examin”, “world”}\}$$

- 2 Codify the document  $d$  as a frequency vector

$$\mathbf{d} = (0, 1, 2, 1, 0).$$

- 3 Standardize to remove length effects:  $\mathbf{d} / \|\mathbf{d}\| \in \Omega_{\#D-1}$ .



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# Von Mises-Fisher distribution

- ▶ The **von Mises-Fisher** (vMF) is the most well known directional density:

$$f_{\text{vMF}}(\mathbf{x}; \boldsymbol{\mu}, \kappa) = C_q(\kappa) \exp \{ \kappa \mathbf{x}^T \boldsymbol{\mu} \}, \quad C_q(\kappa) = \frac{\kappa^{\frac{q-1}{2}}}{(2\pi)^{\frac{q+1}{2}} \mathcal{I}_{\frac{q-1}{2}}(\kappa)}$$

parametrized by a mean  $\boldsymbol{\mu} \in \Omega_q$  and a concentration  $\kappa \geq 0$

- ▶ Density wrt the Lebesgue measure  $\omega_q$  in  $\Omega_q$ .  $\omega_q$  denotes also the area surface of  $\Omega_q$ :

$$\omega_q \equiv \omega_q(\Omega_q) = 2\pi^{\frac{q+1}{2}} / \Gamma\left(\frac{q+1}{2}\right)$$

- ▶ (Isotropic) **Gaussian analogue**:
  - 1 Same MLE characterization property
  - 2 If  $\mathbf{X} \sim \mathcal{N}_{q+1}(\boldsymbol{\mu}, \sigma^2 \mathbf{I}_{q+1})$ , then

$$\mathbf{X} \mid \|\mathbf{X}\| = 1 \sim \text{vMF}\left(\frac{\boldsymbol{\mu}}{\|\boldsymbol{\mu}\|}, \frac{\|\boldsymbol{\mu}\|}{\sigma^2}\right)$$



# Von Mises distribution

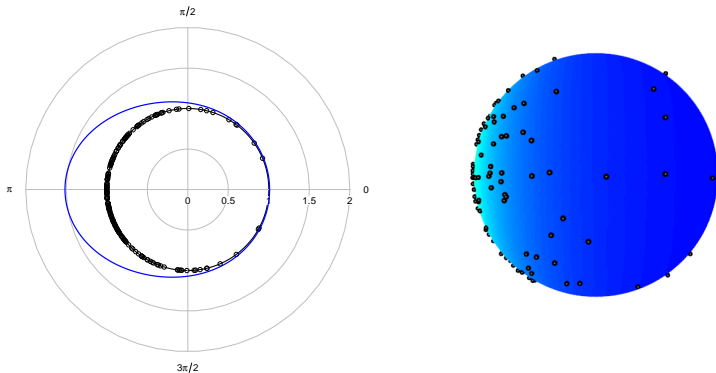


Figure:  $vM(\boldsymbol{\mu}, \kappa)$  density in the circle and the sphere, with  $\boldsymbol{\mu} = (\mathbf{0}_q, 1)$  and  $\kappa = 2$ .



# Von Mises distribution

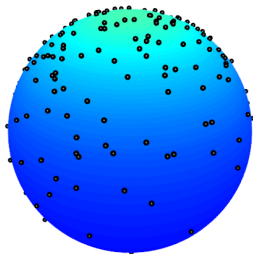
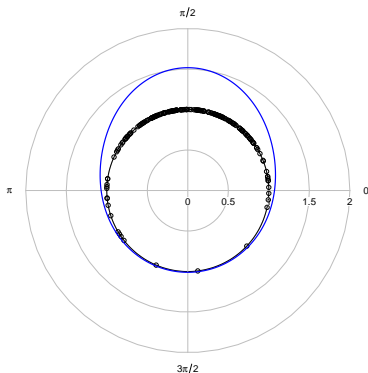


Figure:  $vM(\boldsymbol{\mu}, \kappa)$  density in the circle and the sphere, with  $\boldsymbol{\mu} = (-1, \mathbf{0}_q)$  and  $\kappa = 2$ .

# Von Mises distribution

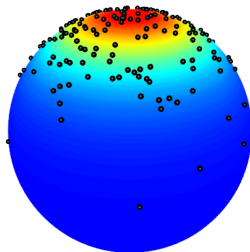
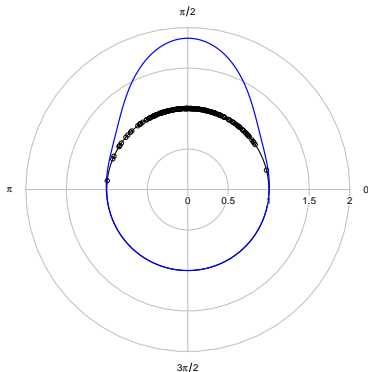


Figure:  $vM(\boldsymbol{\mu}, \kappa)$  density in the circle and the sphere, with  $\boldsymbol{\mu} = (\mathbf{0}_q, 1)$  and  $\kappa = 5$ .

# Von Mises distribution

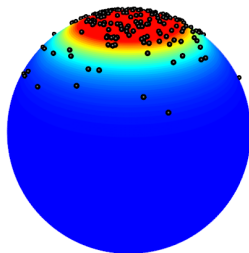
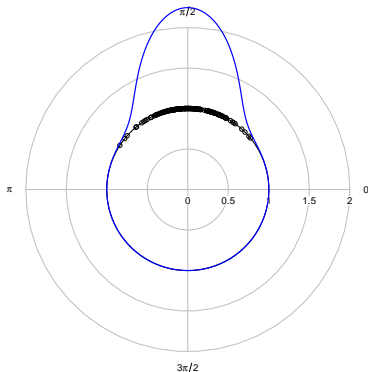
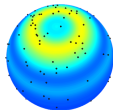


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# Contents of the talk

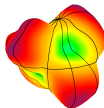
## 1 Part I. Kernel **density** estimation with directional data under rotational symmetry

- ▶ Present a KDE under **rotational symmetry**
- ▶ Study its main **asymptotic properties**
- ▶ Illustrate **empirical performance** through simulations



## 2 Part II. Estimation and testing in linear-directional **regression**

- ▶ Present a **local linear estimator** with directional predictor
- ▶ Build a **goodness-of-fit** test for regression models
- ▶ Apply both to test a common assumption in **bioinformatics**



# Part I

## Kernel density estimation with directional data under rotational symmetry



García-Portugués, E., Ley, C., Verdebout, T. (2017). Kernel density estimation for directional data under rotational symmetry. *Work in progress*.



# Contents of Part I

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## 1 KDE with directional data

## 2 KDE under rotasymmetry

The rotasymmetrizer

Rotasymmetric KDE

## 3 Simulation study



## KDE with directional data

- ▶ For a sample  $\mathbf{X}_1, \dots, \mathbf{X}_n \sim f$ , the Kernel Density Estimator (KDE) for directional data is

$$\hat{f}_h(\mathbf{x}) = \frac{c_{h,q}(L)}{n} \sum_{i=1}^n L\left(\frac{1 - \mathbf{x}^T \mathbf{X}_i}{h^2}\right) = \frac{1}{n} \sum_{i=1}^n L_h(\mathbf{x}, \mathbf{X}_i), \quad \mathbf{x} \in \Omega_q$$



**Bai, Z. D., Rao, C. R. and Zhao, L. C. (1988).** Kernel estimators of density function of directional data. *J. Multivariate Anal.*, 27:24–39

- ▶ Note the  $h^2$  because  $2(1 - \mathbf{x}^T \mathbf{X}_i) = \|\mathbf{x} - \mathbf{X}_i\|^2$
- ▶ Normalizing constant  $c_{h,q}(L)^{-1} = \lambda_q(L) h^q (1 + o(1))$  with

$$\lambda_q(L) = 2^{\frac{q}{2}-1} \omega_{q-1} \int_0^\infty L(r) r^{\frac{q}{2}-1} dr$$

- ▶ “Second moment” of  $L$ :  $b_q(L) = \int_0^\infty L(r) r^{\frac{q}{2}} dr / \int_0^\infty L(r) r^{\frac{q}{2}-1} dr$
- ▶ If  $L(r) = e^{-r}$ , the *vMF kernel*,  $c_{h,q}(L) = e^{1/h^2} C_q(1/h^2)$



# Circular case

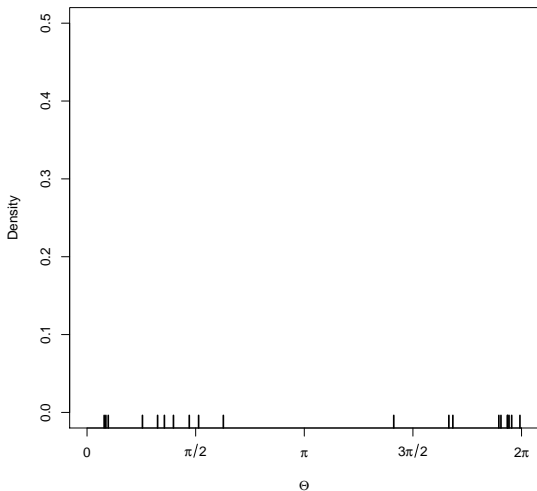


Figure: Construction of the kernel density estimator with  $n = 20$ .





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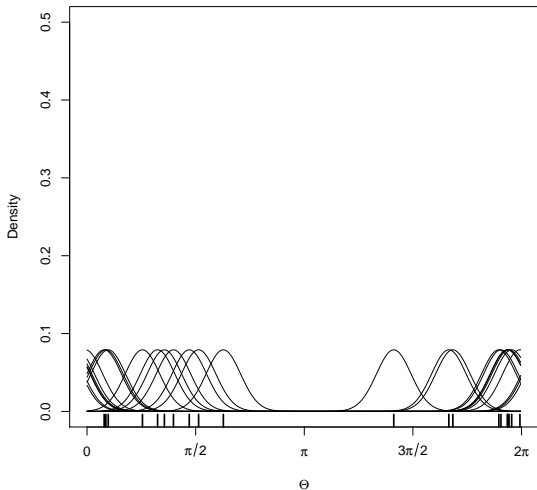


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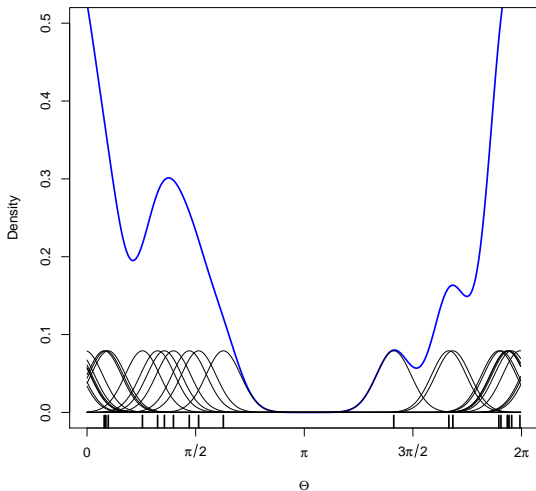


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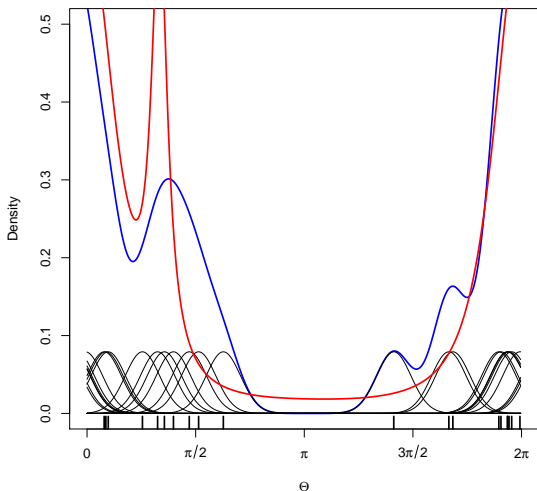


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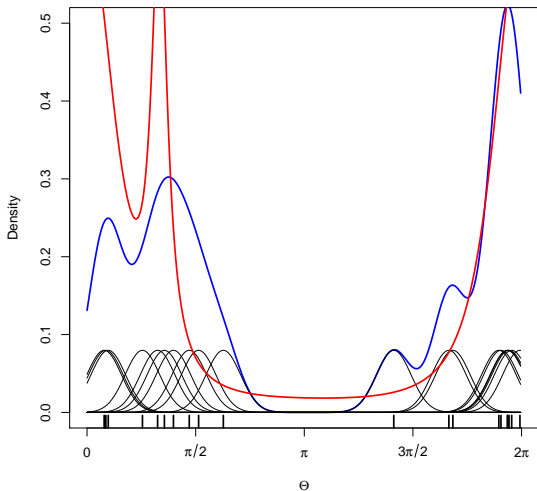


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# KDE construction: spherical case

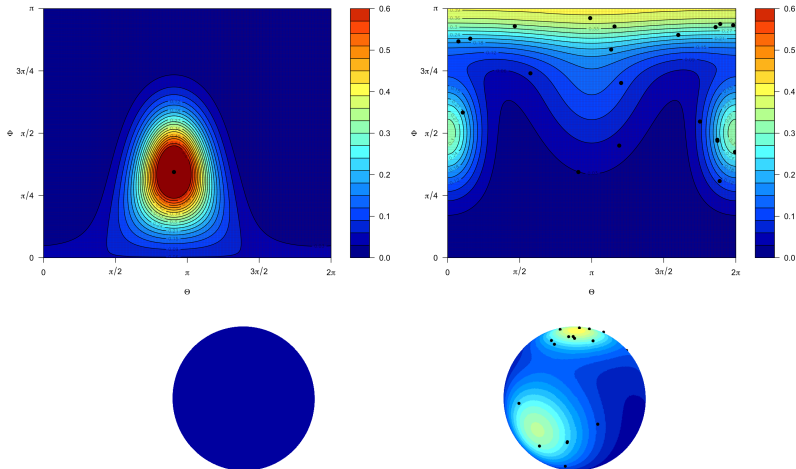


Figure: Left: KDE with  $n = 1$ . Right: true density



# KDE construction: spherical case

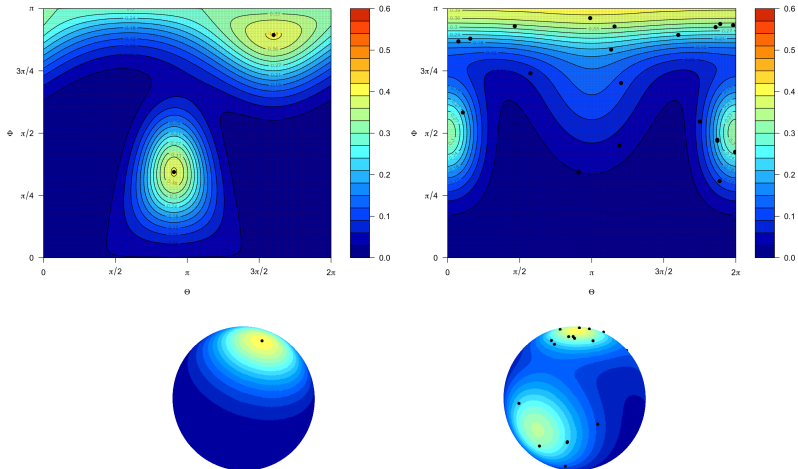


Figure: Left: KDE with  $n = 2$ . Right: true density



# KDE construction: spherical case

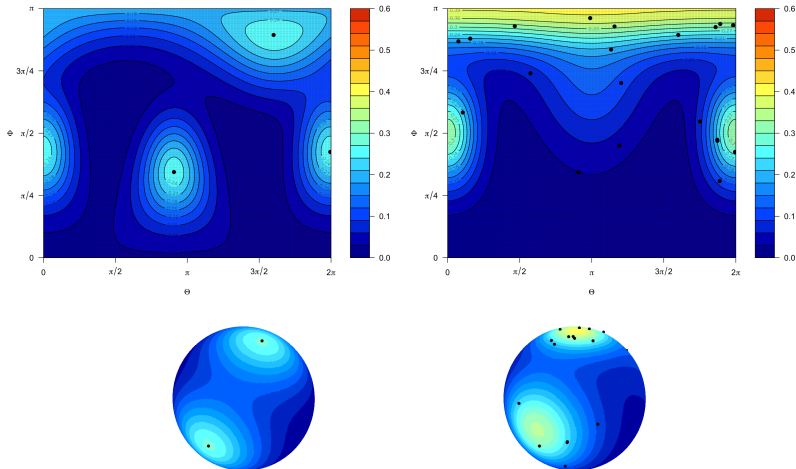


Figure: Left: KDE with  $n = 3$ . Right: true density



# KDE construction: spherical case

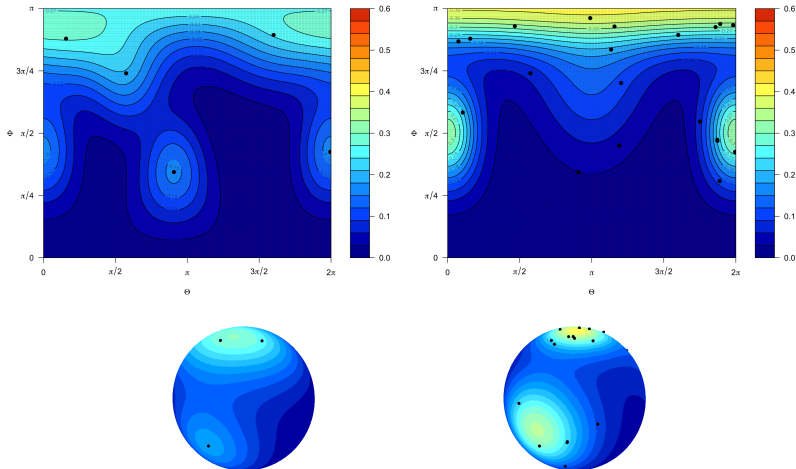


Figure: Left: KDE with  $n = 5$ . Right: true density





# KDE construction: spherical case

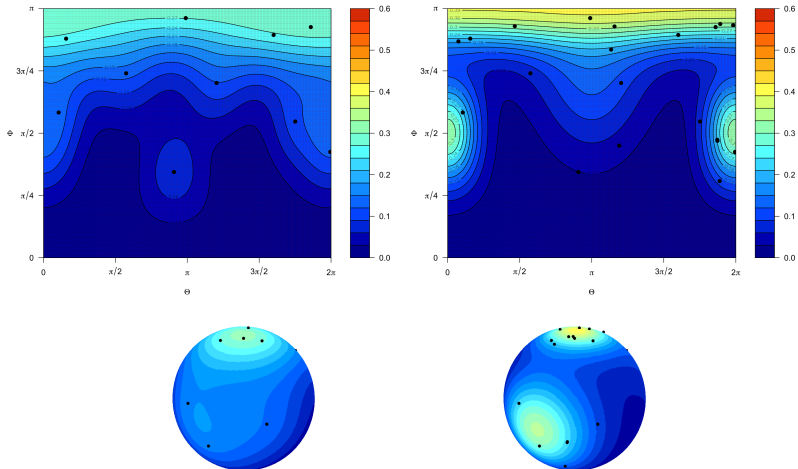


Figure: Left: KDE with  $n = 10$ . Right: true density



# KDE construction: spherical case

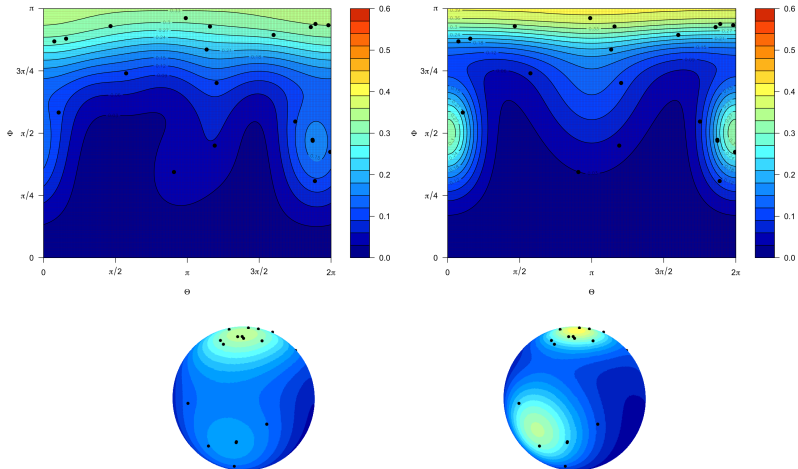


Figure: Left: KDE with  $n = 20$ . Right: true density



# Rotasymmetry I

- ▶ Recurrent assumption:  $\mathbf{X}$  is **rotational symmetric** (or **rotasymmetric**) about some direction  $\theta \in \Omega_q$
- ▶ Circular case: rotasymmetry is **reflective symmetry**
- ▶ High-dimensional situation: rotasymmetry is behind many **celebrated distributions**

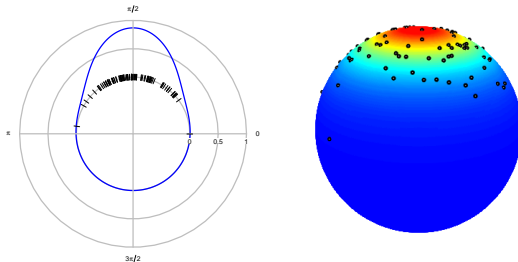


Figure: Rotasymmetry in the circular and spherical cases



# Rotasymmetry II

## Proposition (Rotasymmetry characterization)

Let  $\mathbf{X}$  a directional rv with density  $f$ . These statements are equivalent:

- 1  $\mathbf{X} \stackrel{d}{=} \mathbf{O}\mathbf{X}$ , where  $\mathbf{O} = \boldsymbol{\theta}\boldsymbol{\theta}^T + \sum_{i=1}^q \mathbf{b}_i\mathbf{b}_i^T$  is a rotation matrix on  $\mathbb{R}^{q+1}$  that fixes  $\boldsymbol{\theta} \in \Omega_q$
- 2  $f(\mathbf{x}) = g(\mathbf{x}^T\boldsymbol{\theta})$ ,  $\forall \mathbf{x} \in \Omega_q$ , where  $g : [-1, 1] \rightarrow \mathbb{R}^+$  is a **link** such that

$$f^*(t) = \omega_{q-1}g(t)(1-t^2)^{\frac{q}{2}-1} \text{ is a density in } [-1, 1]$$

- ▶ Rotasymmetry is related with the **tangent-normal decomposition**:

$$\mathbf{x} = t\boldsymbol{\theta} + (1-t^2)^{\frac{1}{2}}\mathbf{B}_\theta\xi$$

with  $t = \mathbf{x}^T\boldsymbol{\theta} \in [-1, 1]$ ,  $\xi \in \Omega_{q-1}$  and  $\mathbf{B}_\theta = (\mathbf{b}_1, \dots, \mathbf{b}_q)_{(q+1) \times q}$  such that  $\mathbf{B}_\theta^T\mathbf{B}_\theta = \mathbf{I}_q$  and  $\mathbf{B}_\theta\mathbf{B}_\theta^T = \mathbf{I}_{q+1} - \boldsymbol{\theta}\boldsymbol{\theta}^T$

- ▶ **No monotonicity** required in  $g$ , axial variables are covered as well



# The rotasymmetrizer

## Definition (Rotasymmetrizer)

The *rotasymmetrizer* around  $\theta$ ,  $R_\theta$ , transforms a function  $f : \Omega_q \rightarrow \mathbb{R}$  into

$$R_\theta f(\mathbf{x}) := \frac{1}{\omega_{q-1}} \int_{\Omega_{q-1}} f(\mathbf{x}_{\theta, \xi}) \omega_{q-1}(d\xi),$$

with  $\mathbf{x}_{\theta, \xi} = (\mathbf{x}^T \theta) \theta + (1 - (\mathbf{x}^T \theta)^2)^{\frac{1}{2}} \mathbf{B}_\theta \xi$

- ▶ For point  $\mathbf{x} \in \Omega_q$ , the operator **averages out** the density along the points sharing the same **colatitude** (wrt  $\theta$ )
- ▶ Intuitively: parallel redistribution of probability mass

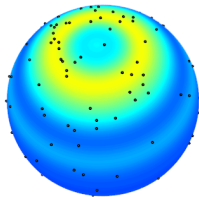
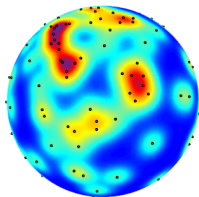


Figure: Input and output of  $R_\theta$  with  $\theta = (0, 0, 1)$



# Properties

## Proposition (Rotasymmetrizer properties)

Let be  $f, f_1, f_2 : \Omega_q \rightarrow \mathbb{R}^+$  directional densities and  $\theta \in \Omega_q$ .

- ① **Invariance** from different matrices  $\mathbf{B}_\theta$ :

$$\int_{\Omega_{q-1}} f(\mathbf{x}_\theta, \xi, 1) \omega_{q-1}(d\xi) = \int_{\Omega_{q-1}} f(\mathbf{x}_\theta, \xi, 2) \omega_{q-1}(d\xi),$$

with  $\mathbf{x}_{\theta, \xi, k} = (\mathbf{x}^T \theta) \theta + (1 - (\mathbf{x}^T \theta)^2)^{\frac{1}{2}} \mathbf{B}_{\theta, k} \xi$ ,  $k = 1, 2$

- ② **Linearity**:  $R_\theta(\lambda_1 f_1 + \lambda_2 f_2)(\mathbf{x}) = \lambda_1 R_\theta f_1(\mathbf{x}) + \lambda_2 R_\theta f_2(\mathbf{x})$
- ③ **Density preservation**:  $R_\theta f$  is a density
- ④ **Characterization**:  $R_\theta f = f \iff f$  is rotasymmetric around  $\theta$
- ⑤ **Explicit expression for the vMF density**:

$$R_\theta f_{\text{vMF}}(\mathbf{x}; \boldsymbol{\mu}, \kappa) = \frac{C_q(\kappa) \exp\{\kappa \mathbf{x}^T \theta \boldsymbol{\mu}^T \theta\}}{\omega_{q-1} C_{q-1}(\kappa [(1 - (\mathbf{x}^T \theta)^2)(1 - (\boldsymbol{\mu}^T \theta)^2)]^{\frac{1}{2}})}$$



# Rotasymmetric KDE

- ▶ Goal: estimate semiparametrically  $f$  under rotasymmetry

## Definition (Rotasymmetric KDE)

The *rotasymmetric KDE (RKDE)* is the application of the rotasymmetrizer to the usual KDE:

$$\hat{f}_{h,\theta}(\mathbf{x}) := R_{\theta} \hat{f}_h(\mathbf{x}) = \frac{1}{n} \sum_{i=1}^n L_{h,\theta}(\mathbf{x}, \mathbf{X}_i),$$

$$\text{with } L_{h,\theta}(\mathbf{x}, \mathbf{X}_i) = \frac{c_{h,q}(L)}{\omega_{q-1}} \int_{\Omega_{q-1}} L\left(\frac{1 - \mathbf{x}_{\theta,\xi}^T \mathbf{X}_i}{h^2}\right) \omega_{q-1}(d\xi)$$

- ▶ The rotasymmetric vMF kernel has an explicit expression:

$$L_{h,\theta}(\mathbf{x}, \mathbf{X}_i) = \frac{C_q(1/h^2) \exp\{\mathbf{x}^T \boldsymbol{\theta} \mathbf{X}_i^T \boldsymbol{\theta} / h^2\}}{\omega_{q-1} C_{q-1}\left(\left[(1 - (\mathbf{x}^T \boldsymbol{\theta})^2)(1 - (\mathbf{X}_i^T \boldsymbol{\theta})^2)\right]^{\frac{1}{2}} / h^2\right)}$$

- ▶ The order of the normalizing constant is  $\mathcal{O}(h^{-1})$



# Comparison of kernels

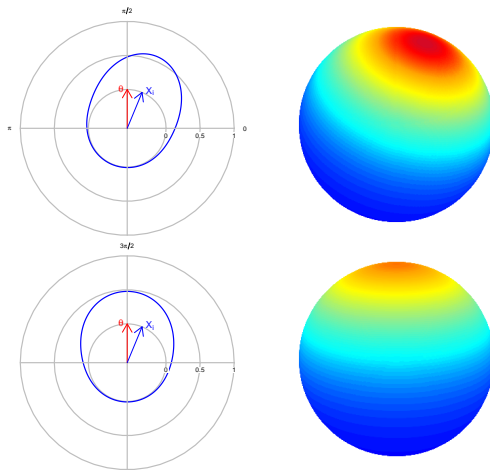


Figure: Kernels for the KDE (upper row) and their RKDE counterparts (lower), with  $\theta = (\mathbf{0}_q, 1)$ . The kernels have the same bandwidth





# Comparison of kernels

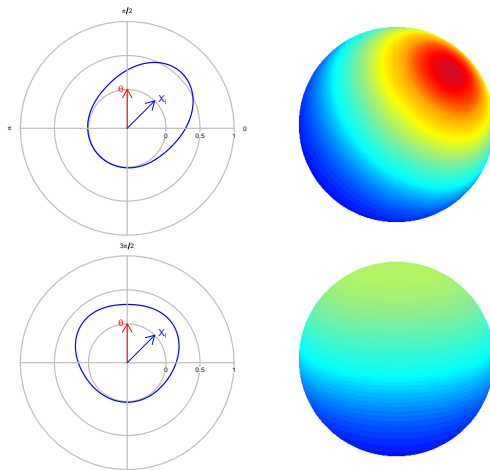


Figure: Kernels for the KDE (upper row) and their RKDE counterparts (lower), with  $\theta = (\mathbf{0}_q, 1)$ . The kernels have the same bandwidth



# Comparison of kernels

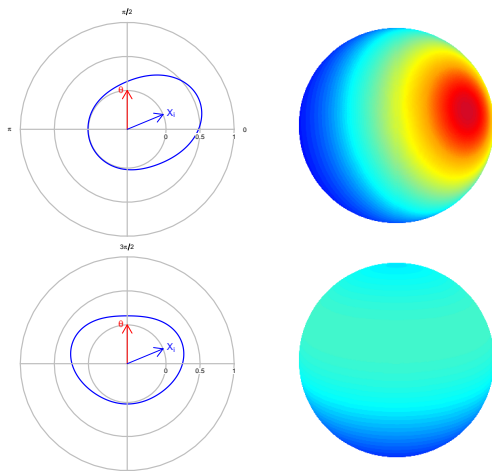


Figure: Kernels for the KDE (upper row) and their RKDE counterparts (lower), with  $\theta = (\mathbf{0}_q, 1)$ . The kernels have the same bandwidth



# Comparison of kernels

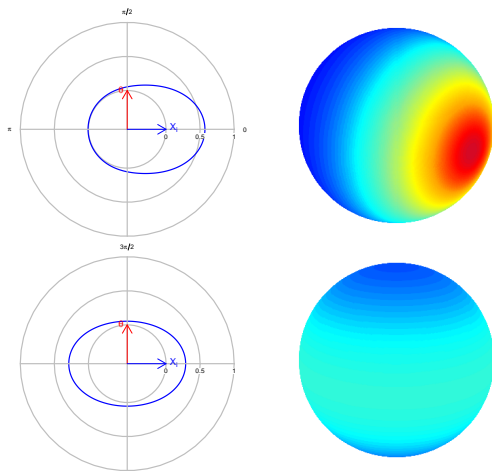


Figure: Kernels for the KDE (upper row) and their RKDE counterparts (lower), with  $\theta = (\mathbf{0}_q, 1)$ . The kernels have the same bandwidth



# Comparison of kernels

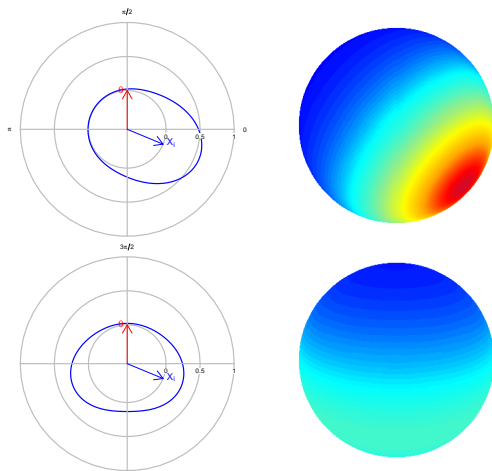


Figure: Kernels for the KDE (upper row) and their RKDE counterparts (lower), with  $\theta = (\mathbf{0}_q, 1)$ . The kernels have the same bandwidth



# Comparison of kernels

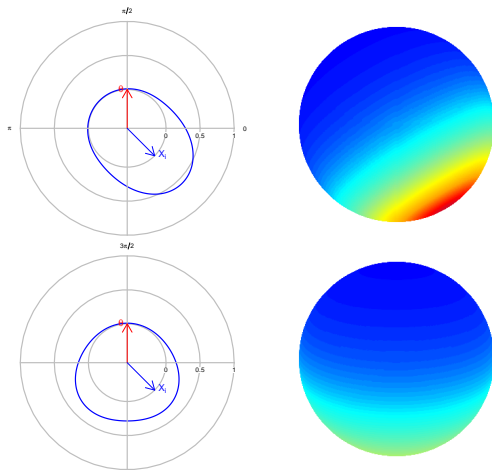


Figure: Kernels for the KDE (upper row) and their RKDE counterparts (lower), with  $\theta = (\mathbf{0}_q, 1)$ . The kernels have the same bandwidth



# Comparison of kernels

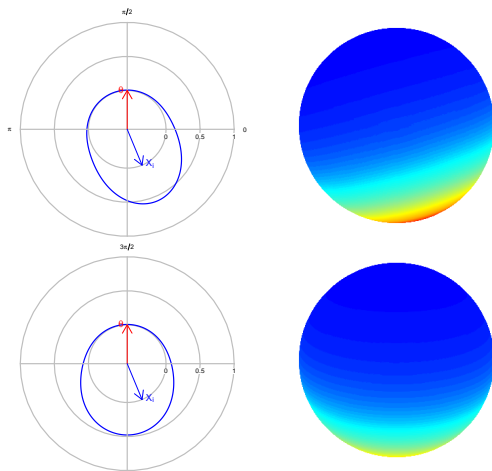


Figure: Kernels for the KDE (upper row) and their RKDE counterparts (lower), with  $\theta = (\mathbf{0}_q, 1)$ . The kernels have the same bandwidth



# Comparison of kernels

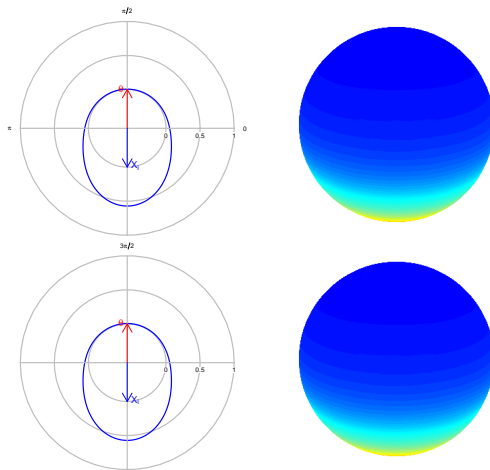


Figure: Kernels for the KDE (upper row) and their RKDE counterparts (lower), with  $\theta = (\mathbf{0}_q, 1)$ . The kernels have the same bandwidth



# Connections with KDE in $[-1, 1]$

- ▶ The RKDE kernels **only** depend on the **projected sample**  $T_i = \mathbf{X}_i^T \boldsymbol{\theta}$  and the **projected point**  $t = \mathbf{x}^T \boldsymbol{\theta}$
- ▶ RKDE is equivalent to KDE on  $[-1, 1]$  with bounded kernels adapted to capture the spikes of  $f^*(t) = \omega_{q-1} g(t)(1-t^2)^{\frac{q}{2}-1}$
- ▶ Boundary bias is  $\mathcal{O}(h^2)$  without any corrections

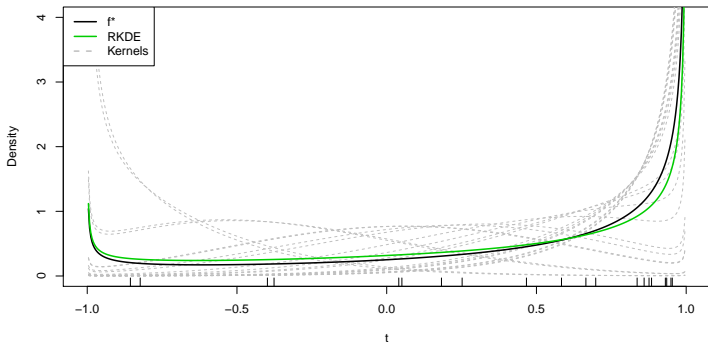


Figure: KDE of  $f^*$  with  $g(t) = C_q(\kappa) \exp\{\kappa t\}$ ,  $\kappa = 1$  and  $q = 1$





# Connections with KDE in $[-1, 1]$

- ▶ The RKDE kernels **only** depend on the **projected sample**  $T_i = \mathbf{X}_i^T \boldsymbol{\theta}$  and the **projected point**  $t = \mathbf{x}^T \boldsymbol{\theta}$
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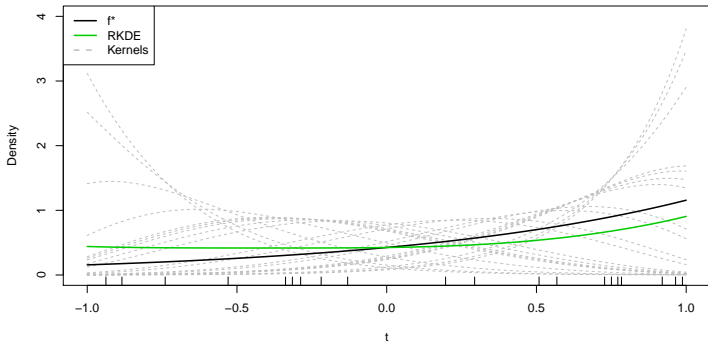


Figure: KDE of  $f^*$  with  $g(t) = C_q(\kappa) \exp\{\kappa t\}$ ,  $\kappa = 1$  and  $q = 2$



## Connections with KDE in $[-1, 1]$

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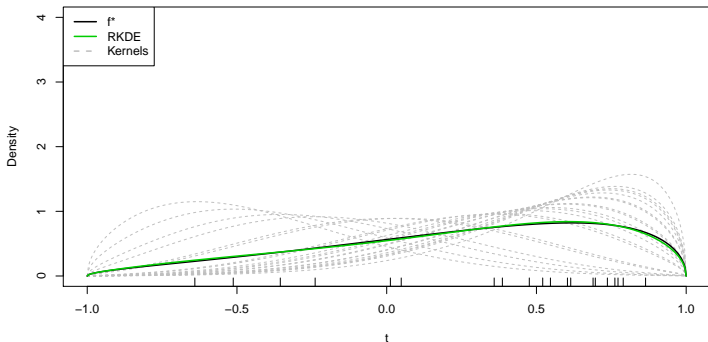


Figure: KDE of  $f^*$  with  $g(t) = C_q(\kappa) \exp\{\kappa t\}$ ,  $\kappa = 1$  and  $q = 3$



## Connections with KDE in $[-1, 1]$

- ▶ The RKDE kernels **only** depend on the **projected sample**  $T_i = \mathbf{X}_i^T \boldsymbol{\theta}$  and the **projected point**  $t = \mathbf{x}^T \boldsymbol{\theta}$
- ▶ RKDE is equivalent to KDE on  $[-1, 1]$  with bounded kernels adapted to capture the spikes of  $f^*(t) = \omega_{q-1} g(t) (1-t^2)^{\frac{q}{2}-1}$
- ▶ Boundary bias is  $\mathcal{O}(h^2)$  without any corrections

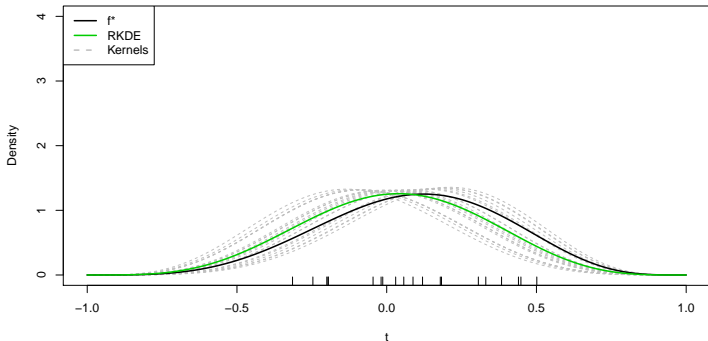


Figure: KDE of  $f^*$  with  $g(t) = C_q(\kappa) \exp\{\kappa t\}$ ,  $\kappa = 1$  and  $q = 10$



# Connections with KDE in $[-1, 1]$

- ▶ The RKDE kernels **only** depend on the **projected sample**  $T_i = \mathbf{X}_i^T \boldsymbol{\theta}$  and the **projected point**  $t = \mathbf{x}^T \boldsymbol{\theta}$
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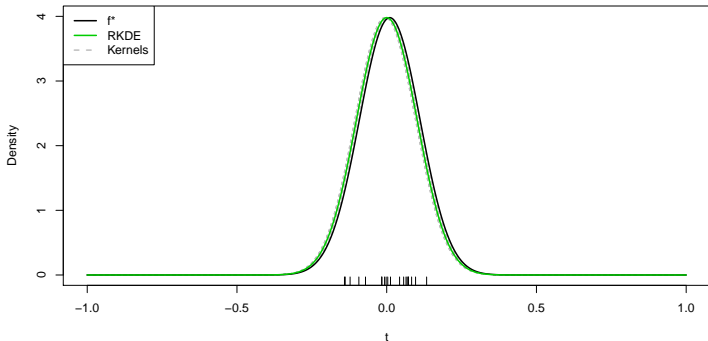


Figure: KDE of  $f^*$  with  $g(t) = C_q(\kappa) \exp\{\kappa t\}$ ,  $\kappa = 1$  and  $q = 100$



# Bias ( $\theta$ known)

► **Assumptions:**

**A1**  $f$  is extended by  $f(\mathbf{x}/\|\mathbf{x}\|)$  and is twice continuously differentiable

**A2**  $L : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is continuous, bounded and has exponential decay

**A3-1** The sequence  $h = h_n$  satisfies  $h \rightarrow 0$  and  $nh \rightarrow \infty$

**A3-q** The sequence  $h = h_n$  satisfies  $h \rightarrow 0$  and  $nh^q \rightarrow \infty$

► **A3-q** is required for consistency at  $\mathbf{x} = \pm\theta$  (note **A3-q**  $\Rightarrow$  **A3-1**)

## Proposition (Bias, $\theta$ known)

Under **A1–A3-1** and uniformly in  $\mathbf{x} \in \Omega_q$ ,

$$\mathbb{E} \left[ \hat{f}_{h,\theta}(\mathbf{x}) \right] = R_\theta f(\mathbf{x}) + \frac{b_q(L)}{q} \text{tr} [R_\theta \mathcal{H}f(\mathbf{x})] h^2 + o(h^2)$$

If rotasymmetry holds, then  $R_\theta f = f$  and the bias is KDE's one



# Variance ( $\theta$ known)

## Proposition (Variance, $\theta$ known)

Under **A1–A2**, **A3** if  $(\mathbf{x}^T \boldsymbol{\theta})^2 < 1$  and **A4** otherwise,

$$\text{Var} \left[ \hat{f}_{h,\theta}(\mathbf{x}) \right] = C_{\mathbf{x}^T \boldsymbol{\theta}, q, L}(h) \frac{R_{\boldsymbol{\theta}} f(\mathbf{x})}{n} (1 + o(1)) - \frac{(R_{\boldsymbol{\theta}} f(\mathbf{x}))^2}{n}$$

uniformly in  $\mathbf{x} \in \Omega_q$ , where

$$C_{\mathbf{x}^T \boldsymbol{\theta}, q, L}(h) \propto \begin{cases} \frac{\lambda_q(L^2) \lambda_q(L)^{-2}}{h^q}, & (\mathbf{x}^T \boldsymbol{\theta})^2 = 1, q \geq 1, \\ \frac{\lambda_1(L^2) \lambda_1(L)^{-2}}{2h}, & (\mathbf{x}^T \boldsymbol{\theta})^2 < 1, q = 1, \\ \frac{\lambda_q(L)^2 \lambda_{q-1}(L)^{-2}}{\omega_{q-1} (1 - (\mathbf{x}^T \boldsymbol{\theta})^2)^{\frac{1}{2}} h}, & (\mathbf{x}^T \boldsymbol{\theta})^2 < 1, q \geq 2 \end{cases}$$

- ▶ The asymptotic constant of the variance increases with  $q \rightarrow \infty$  since  $\omega_{q-1} \rightarrow 0!$  (but slowly than KDE's)



# Spherical area surface

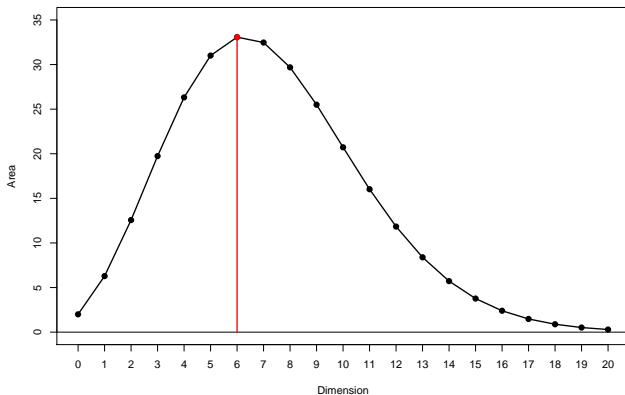


Figure: Spherical surface  $\omega_q = 2\pi^{\frac{q+1}{2}} / \Gamma\left(\frac{q+1}{2}\right)$

- ▶ The area of  $\Omega_q$  tends to zero, but not monotonically
- ▶ *Weird* maximum at dimension  $q = 6$
- ▶  $[-1, 1]^q$  touches  $\Omega_q$  in  $2^q$  points, yet its area tends to infinity!



# Key orders & asymptotic normality

Concept	KDE ( $\checkmark/\times$ rotasym.)	RKDE ( $\checkmark$ rotasym.)	RKDE ( $\times$ rotasym.)
Bias	$\mathcal{O}(h^2)$	$\mathcal{O}(h^2)$	$\mathcal{O}(R_{\theta}f(\mathbf{x}) - f(\mathbf{x}))$
Variance	$\mathcal{O}((nh^q)^{-1})$	$\mathcal{O}((nh)^{-1})$	$\mathcal{O}((nh)^{-1})$
Optimal AMISE	$\mathcal{O}(n^{-\frac{4}{4+q}})$	$\mathcal{O}(n^{-\frac{4}{5}})$	$\mathcal{O}(\int (R_{\theta}f - f)^2)$

Table: Summary of the KDE and RKDE key orders

## Corollary (Pointwise asymptotic normality, $\theta$ known)

Under **A1–A2**, **A3** if  $(\mathbf{x}^T \boldsymbol{\theta})^2 < 1$  and **A4** otherwise,

$$a_n \left( \hat{f}_{h,\theta}(\mathbf{x}) - f(\mathbf{x}) \right) \xrightarrow{d} \mathcal{N} \left( R_{\theta}f(\mathbf{x}) - f(\mathbf{x}), C_{\mathbf{x}^T \boldsymbol{\theta}, q, L}(1) \right),$$

where  $a_n = \sqrt{nh}$  if  $(\mathbf{x}^T \boldsymbol{\theta})^2 < 1$  and  $a_n = \sqrt{nh^q}$  otherwise





# Simulation study

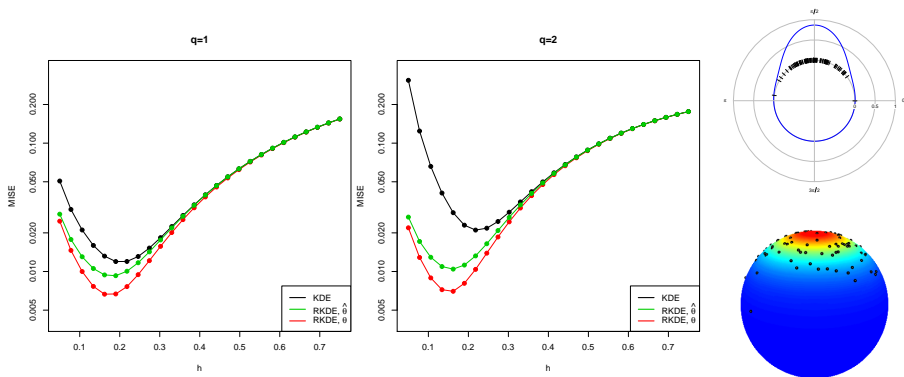


Figure: Performance of the three kernel estimators with  $q = 1$  (left) and  $q = 2$  (right), with  $n = 100$

Ratios optimal MISEs	$q = 1$	$q = 2$	$q = 3$	$q = 4$	$q = 5$	$q = 6$
KDE/RKDE, $\hat{\theta}$	1.796	2.999	4.065	5.643	5.871	8.019
KDE/RKDE, $\hat{\theta}$	1.289	2.014	2.537	3.035	3.207	3.467



# Simulation study

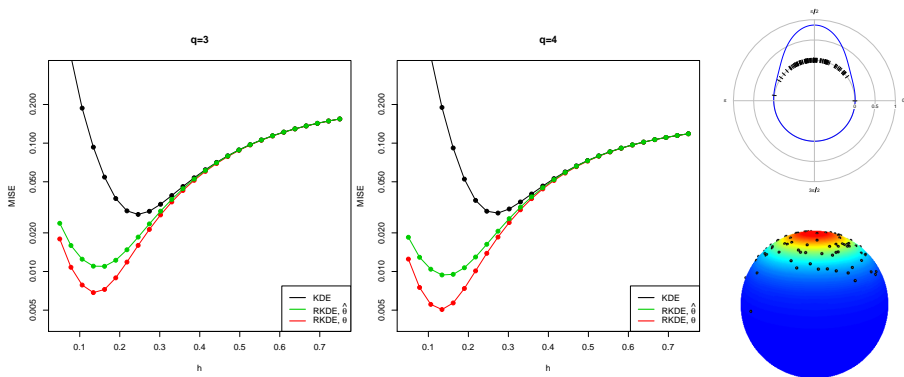


Figure: Performance of the three kernel estimators with  $q = 3$  (left) and  $q = 4$  (right), with  $n = 100$

Ratios optimal MISEs	$q = 1$	$q = 2$	$q = 3$	$q = 4$	$q = 5$	$q = 6$
KDE/RKDE, $\theta$	1.796	2.999	4.065	5.643	5.871	8.019
KDE/RKDE, $\hat{\theta}$	1.289	2.014	2.537	3.035	3.207	3.467



# Simulation study

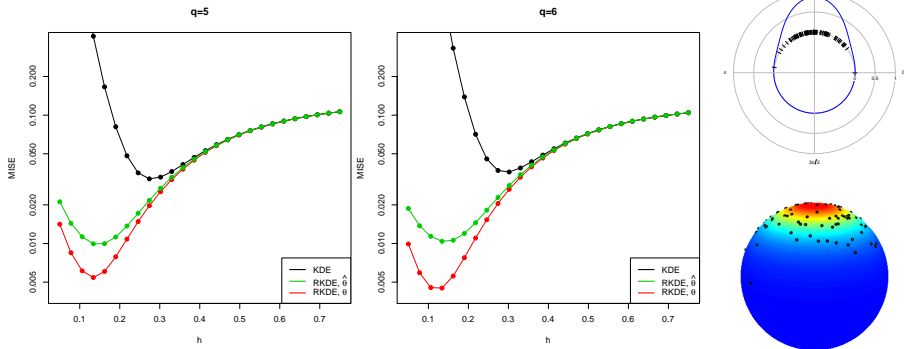


Figure: Performance of the three kernel estimators with  $q = 5$  (left) and  $q = 6$  (right), with  $n = 100$

Ratios optimal MISEs	$q = 1$	$q = 2$	$q = 3$	$q = 4$	$q = 5$	$q = 6$
KDE/RKDE, $\hat{\theta}$	1.796	2.999	4.065	5.643	5.871	8.019
KDE/RKDE, $\hat{\theta}$	1.289	2.014	2.537	3.035	3.207	3.467



## Part II

# Estimation and testing in linear-directional regression



García-Portugués, E., Van Keilegom, I., Crujeiras, R. and González-Manteiga, W. (2016). Testing parametric models in linear-directional regression. *Scand. J. Stat.*, 43(4):1178–1191.



# Contents of Part II

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- 1 **Nonparametric estimation of the regression**
- 2 **Goodness-of-fit tests for models with directional predictor**
  - Asymptotic distribution
  - Calibration in practice
- 3 **Data application**



# Regression with directional data

- ▶ Let  $(\mathbf{X}, Y)$  be a rv with support in  $\Omega_q \times \mathbb{R}$  and  $\mathbf{X}$  having density  $f$
- ▶ Consider the location-scale regression model

$$Y = m(\mathbf{X}) + \sigma(\mathbf{X})\varepsilon \quad \text{with} \quad \begin{cases} m(\mathbf{x}) = \mathbb{E}[Y|\mathbf{X} = \mathbf{x}], \\ \sigma^2(\mathbf{x}) = \text{Var}[Y|\mathbf{X} = \mathbf{x}], \end{cases}$$

with  $\mathbb{E}[\varepsilon|\mathbf{X}] = 0$ ,  $\mathbb{E}[\varepsilon^2|\mathbf{X}] = 1$  and  $\mathbb{E}[|\varepsilon|^3|\mathbf{X}]$  and  $\mathbb{E}[\varepsilon^4|\mathbf{X}]$  bounded rv's

- ▶ **Goal: estimate  $m$  nonparametrically from  $\{(\mathbf{X}_i, Y_i)\}_{i=1}^n$**
- ▶ Taylor expansions are required, so the first condition is:
  - A1  $m$  and  $f$  are extended as  $m(\mathbf{x}/\|\mathbf{x}\|)$  and  $f(\mathbf{x}/\|\mathbf{x}\|)$ .  $m$  is third and  $f$  is twice continuously differentiable and  $f$  is bounded away from zero



# Estimator

- ▶ Let  $\mathbf{x}, \mathbf{X}_i \in \Omega_q$ . The one term Taylor expansion of  $m$  is:

$$m(\mathbf{X}_i) = m(\mathbf{x}) + \nabla m(\mathbf{x})^T (\mathbf{X}_i - \mathbf{x}) + \mathcal{O}(\|\mathbf{X}_i - \mathbf{x}\|^2)$$



# Estimator

- ▶ Let  $\mathbf{x}, \mathbf{X}_i \in \Omega_q$ . The one term Taylor expansion of  $m$  is:

$$m(\mathbf{X}_i) = m(\mathbf{x}) + \nabla m(\mathbf{x})^T (\mathbf{I}_{q+1} - \mathbf{x}\mathbf{x}^T) (\mathbf{X}_i - \mathbf{x}) + \mathcal{O}(\|\mathbf{X}_i - \mathbf{x}\|^2)$$





# Estimator

- ▶ Let  $\mathbf{x}, \mathbf{X}_i \in \Omega_q$ . The one term Taylor expansion of  $m$  is:

$$m(\mathbf{X}_i) = m(\mathbf{x}) + \nabla m(\mathbf{x})^T \mathbf{B}_x \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}) + \mathcal{O}(\|\mathbf{X}_i - \mathbf{x}\|^2)$$



# Estimator

- ▶ Let  $\mathbf{x}, \mathbf{X}_i \in \Omega_q$ . The one term Taylor expansion of  $m$  is:

$$m(\mathbf{X}_i) = m(\mathbf{x}) + \nabla m(\mathbf{x})^T \mathbf{B}_x \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}) + \mathcal{O}(\|\mathbf{X}_i - \mathbf{x}\|^2)$$

$$\approx \beta_0 + (\beta_1, \dots, \beta_q)^T \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}),$$

with  $\mathbf{B}_x = (\mathbf{b}_1, \dots, \mathbf{b}_q)_{(q+1) \times q}$  such that  $\mathbf{B}_x \mathbf{B}_x^T = \mathbf{I}_{q+1} - \mathbf{x} \mathbf{x}^T$ ,  
 $\beta_0 = m(\mathbf{x})$  and  $(\beta_1, \dots, \beta_q) = \mathbf{B}_x^T \nabla m(\mathbf{x})$



# Estimator

- ▶ Let  $\mathbf{x}, \mathbf{X}_i \in \Omega_q$ . The one term Taylor expansion of  $m$  is:

$$\begin{aligned}m(\mathbf{X}_i) &= m(\mathbf{x}) + \nabla m(\mathbf{x})^T \mathbf{B}_x \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}) + \mathcal{O}(\|\mathbf{X}_i - \mathbf{x}\|^2) \\ &\approx \beta_0 + (\beta_1, \dots, \beta_q)^T \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}),\end{aligned}$$

with  $\mathbf{B}_x = (\mathbf{b}_1, \dots, \mathbf{b}_q)_{(q+1) \times q}$  such that  $\mathbf{B}_x \mathbf{B}_x^T = \mathbf{I}_{q+1} - \mathbf{x}\mathbf{x}^T$ ,  
 $\beta_0 = m(\mathbf{x})$  and  $(\beta_1, \dots, \beta_q) = \mathbf{B}_x^T \nabla m(\mathbf{x})$

- ▶ Weighted minimum least squares problem:

$$\min_{\beta \in \mathbb{R}^{q+1}} \sum_{i=1}^n \left( Y_i - \beta_0 - \delta_{p,1} (\beta_1, \dots, \beta_q)^T \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}) \right)^2 L_h(\mathbf{x}, \mathbf{X}_i)$$



# Estimator

- ▶ Let  $\mathbf{x}, \mathbf{X}_i \in \Omega_q$ . The one term Taylor expansion of  $m$  is:

$$m(\mathbf{X}_i) = m(\mathbf{x}) + \nabla m(\mathbf{x})^T \mathbf{B}_x \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}) + \mathcal{O}(\|\mathbf{X}_i - \mathbf{x}\|^2) \\ \approx \beta_0 + (\beta_1, \dots, \beta_q)^T \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}),$$

with  $\mathbf{B}_x = (\mathbf{b}_1, \dots, \mathbf{b}_q)_{(q+1) \times q}$  such that  $\mathbf{B}_x \mathbf{B}_x^T = \mathbf{I}_{q+1} - \mathbf{x} \mathbf{x}^T$ ,  
 $\beta_0 = m(\mathbf{x})$  and  $(\beta_1, \dots, \beta_q) = \mathbf{B}_x^T \nabla m(\mathbf{x})$

- ▶ Weighted minimum least squares problem:

$$\min_{\beta \in \mathbb{R}^{q+1}} \sum_{i=1}^n \left( Y_i - \beta_0 - \delta_{p,1} (\beta_1, \dots, \beta_q)^T \mathbf{B}_x^T (\mathbf{X}_i - \mathbf{x}) \right)^2 L_h(\mathbf{x}, \mathbf{X}_i)$$

- ▶ The solution is given by

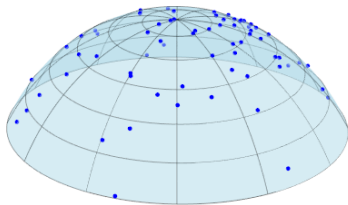
$$\hat{m}_{h,p}(\mathbf{x}) = \mathbf{e}_{1,p}^T (\mathcal{X}_{x,p}^T \mathcal{W}_x \mathcal{X}_{x,p})^{-1} \mathcal{X}_{x,p}^T \mathcal{W}_x \mathbf{Y} = \sum_{i=1}^n W_p^n(\mathbf{x}, \mathbf{X}_i) Y_i,$$

$$\mathcal{X}_{x,1} = \begin{pmatrix} 1 & (\mathbf{X}_1 - \mathbf{x})^T \mathbf{B}_x \\ \vdots & \vdots \\ 1 & (\mathbf{X}_n - \mathbf{x})^T \mathbf{B}_x \end{pmatrix}, \quad \mathcal{W}_x = \text{diag}(L_h(\mathbf{x}, \mathbf{X}_1), \dots, L_h(\mathbf{x}, \mathbf{X}_n))$$

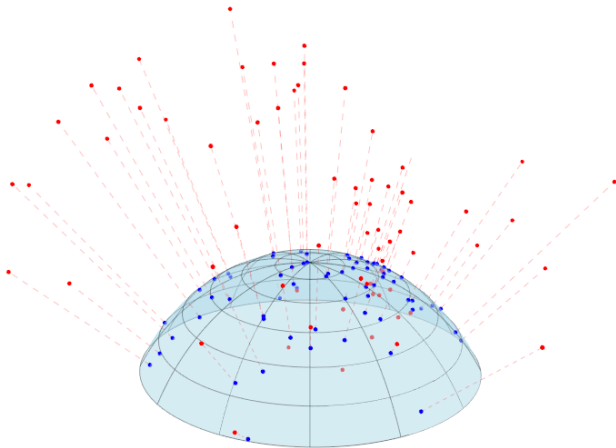


# How does it work?

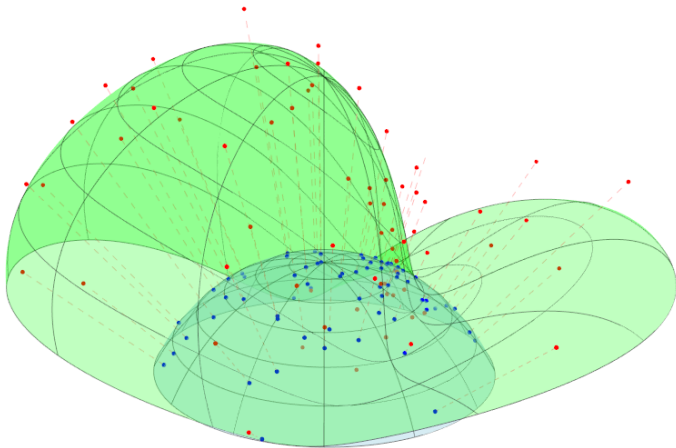
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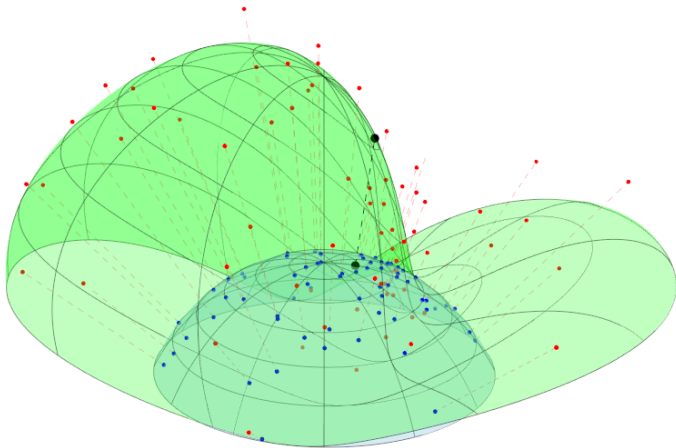
# How does it work?



# How does it work?

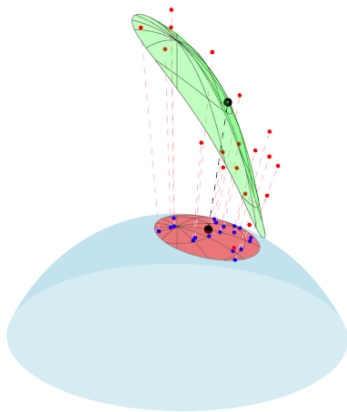


# How does it work?

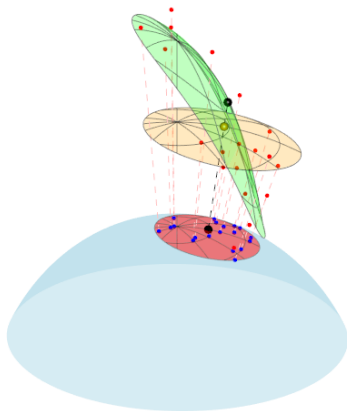




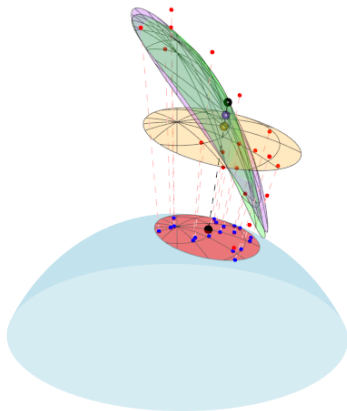
# How does it work?



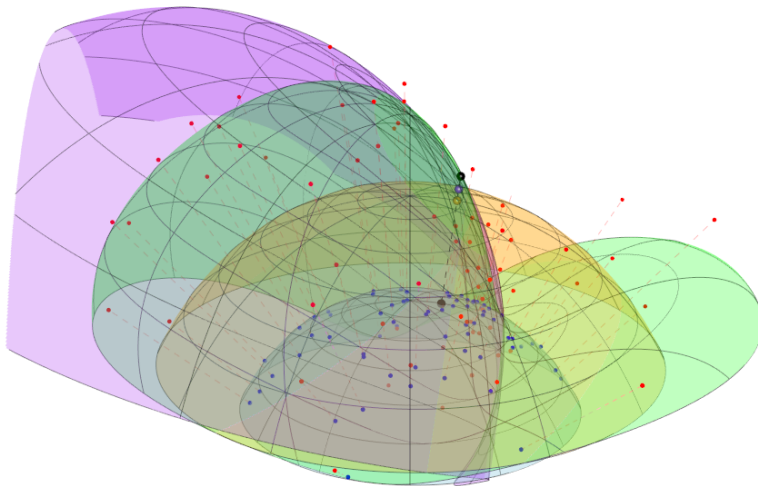
# How does it work?



# How does it work?



# How does it work?



# Output

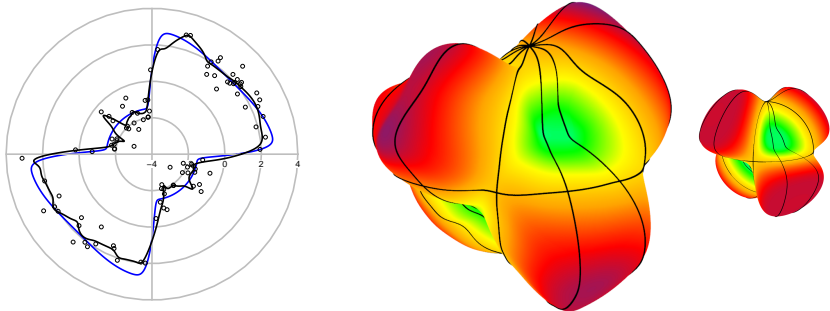


Figure: Local linear estimator with  $n = 100$  for the circle and the sphere

# Testing a parametric model

- ▶ **Goal: check nonparametrically**  $H_0 : m \in \mathcal{M}_\Theta = \{m_\theta : \theta \in \Theta \subset \mathbb{R}^s\}$
- ▶ The statistic is the weighted  $L^2$ -distance between  $\hat{m}_{h,p}$  and the smoothed  $m_{\hat{\theta}}$ :

$$T_n = \int_{\Omega_q} (\hat{m}_{h,p}(\mathbf{x}) - \mathcal{L}_{h,p}m_{\hat{\theta}}(\mathbf{x}))^2 \hat{f}_h(\mathbf{x})w(\mathbf{x})\omega_q(d\mathbf{x}),$$

with  $\mathcal{L}_{h,p}m_{\hat{\theta}}(\mathbf{x}) = \sum_{i=1}^n W_n^p(\mathbf{x}, \mathbf{X}_i) m_{\hat{\theta}}(\mathbf{X}_i)$  the smoothing operator and  $w : \Omega_q \rightarrow \mathbb{R}^+$  a weight function (useful for removing possible boundary effects)



**Alcalá, J. T., Cristóbal, J. A., and González-Manteiga, W. (1999).**

Goodness-of-fit test for linear models based on local polynomials. *Statist. Probab. Lett.*, 42(1):39–46



**Härdle, W. and Mammen, E. (1993).** Comparing nonparametric versus parametric regression fits. *Ann. Statist.*, 21(4):1926–1947



# Asymptotic distribution

## Theorem (Goodness-of-fit for linear-directional models)

Under **A1–A6** and  $H_0 : m \in \mathcal{M}_\Theta$  (i.e.,  $m = m_{\theta_0}$ ),

$$nh^{\frac{q}{2}} \left( T_n - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma_{\theta_0}^2(\mathbf{x}) w(\mathbf{x}) \omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu_{\theta_0}^2),$$

where  $\sigma_{\theta_0}^2(\mathbf{x}) = \mathbb{E}[(Y - m_{\theta_0}(\mathbf{X}))^2 | \mathbf{X} = \mathbf{x}]$  and

$$\begin{aligned} \nu_{\theta_0}^2 &= \int_{\Omega_q} \sigma_{\theta_0}^4(\mathbf{x}) w(\mathbf{x})^2 \omega_q(d\mathbf{x}) \\ &\quad \times \gamma_q \lambda_q(L)^{-4} \int_0^\infty r^{\frac{q}{2}-1} \left\{ \int_0^\infty \rho^{\frac{q}{2}-1} L(\rho) \varphi_q(r, \rho) d\rho \right\}^2 dr \end{aligned}$$

► Conditions:

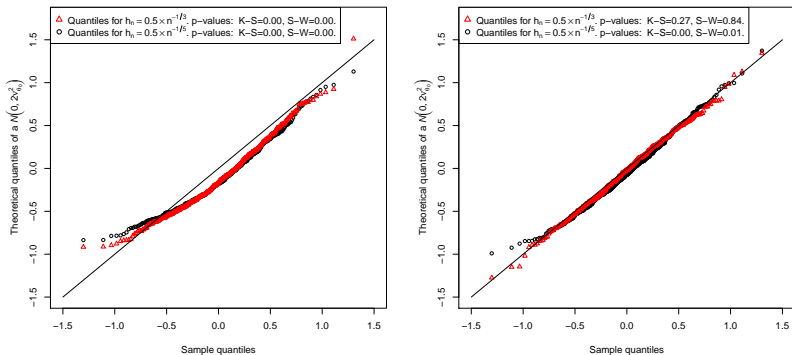
**A5**  $\hat{\theta}$  is such that  $\hat{\theta} - \theta_1 = O_{\mathbb{P}}(n^{-\frac{1}{2}})$ , with  $\theta_1 = \theta_0$  if  $H_0$  holds

**A6**  $m_\theta$  is continuously differentiable as a function of  $\theta$ , being this derivative also continuous for  $\mathbf{x} \in \Omega_q$

► If  $L$  is the von Mises kernel,  $\nu_{\theta_0}^2 = \int_{\Omega_q} \sigma_{\theta_0}^4(\mathbf{x}) w(\mathbf{x})^2 \omega_q(d\mathbf{x}) \times (8\pi)^{-\frac{q}{2}}$



# Empirical evidence



**Figure:** QQ-plot comparing the quantiles of the asymptotic distribution with the sample quantiles for  $\{nh^{\frac{1}{2}}(T_n^j - \frac{\sqrt{\pi}}{4}nh)\}_{j=1}^{500}$  with  $n = 10^2$  (left) and  $n = 5 \times 10^5$  (right)





# Calibration in practice

## Algorithm (Calibration in practice)

To test  $H_0 : m \in \mathcal{M}_\Theta$  from the sample  $\{(\mathbf{X}_i, Y_i)\}_{i=1}^n$ :

- 1 Obtain  $\hat{\theta}$ , set  $\hat{\varepsilon}_i = Y_i - m_{\hat{\theta}}(\mathbf{X}_i)$ ,  $i = 1, \dots, n$  and compute  $T_n$
- 2 Bootstrap resampling. For  $b = 1, \dots, B$ :
  - ▶ Set  $Y_i^* = m_{\hat{\theta}}(\mathbf{X}_i) + \hat{\varepsilon}_i V_i^*$ , where  $V_i^*$  are iid rv's such that  $\mathbb{E}^*[V_i^*] = 0$  and  $\mathbb{E}^*[(V_i^*)^2] = 1$ ,  $i = 1, \dots, n$
  - ▶ Compute  $\hat{\theta}^*$  from  $\{(\mathbf{X}_i, Y_i^*)\}_{i=1}^n$  and  $T_n^{*b}$
- 3 Estimate the  $p$ -value by  $\frac{1}{B} \sum_{b=1}^B \mathbf{1}_{\{T_n \leq T_n^{*b}\}}$

## Theorem (Bootstrap consistency)

Under A1–A4, A5–A6 and A9, conditionally on the sample,

$$nh^{\frac{q}{2}} \left( T_n^* - \frac{\lambda_q(L^2)\lambda_q(L)^{-2}}{nh^q} \int_{\Omega_q} \sigma_{\hat{\theta}_1}^2(\mathbf{x}) w(\mathbf{x}) \omega_q(d\mathbf{x}) \right) \xrightarrow{d} \mathcal{N}(0, 2\nu_{\hat{\theta}_1}^2)$$

in probability. If  $H_0$  holds, then  $\theta_1 = \theta_0$  and  $T_n^* \stackrel{d}{=} T_n$  asymptotically



# Protein structure modelling

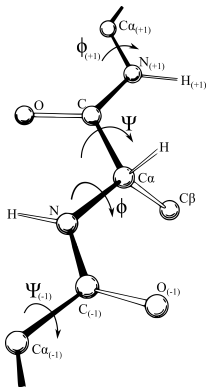


Figure: Backbone and  $C_\alpha$  representation

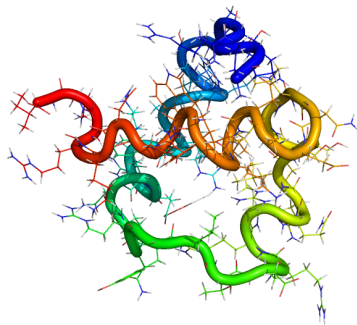


Figure: Cartoon view of a protein



**Boomsma, W., Mardia, K. V., Taylor, C. C., Ferkinghoff-Borg, J., Krogh, A. and Hamelryck, T.** A generative, probabilistic model of local protein structure. *PNAS*, 105(26):8932-8937



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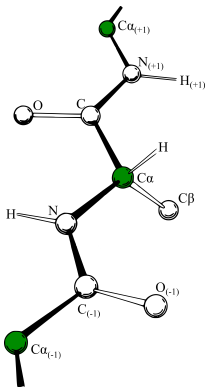


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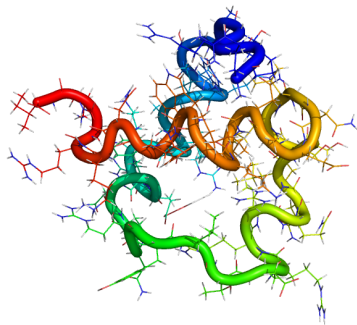


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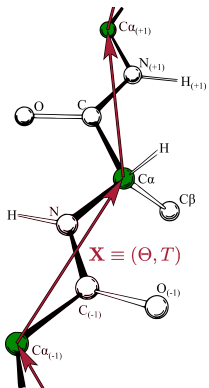


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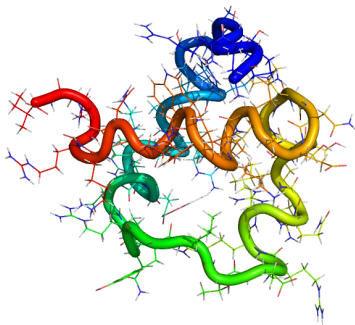


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# Testing in the $C_\alpha$ representation

- ▶ **Goal: test the constant pseudo-bond length assumption:**

$$H_0 : m(\mathbf{x}) = c, c \in \mathbb{R}$$

- ▶ Data:  $n = 18030$  pseudo-angles ( $\mathbf{X} \equiv (\Theta, T)$ ) and pseudo-lengths ( $Y$ ) extracted from 100 high precision protein structures
- ▶ Grid of 10 bandwidths,  $B = 1000$  bootstrap replicates and weight  $w(\theta, \tau) = \mathbf{1}_{\{80 \leq \frac{180}{\pi} \theta \leq 150\}}$
- ▶ **Emphatically rejection of  $H_0$**
- ▶ Exploration of  $m(\theta, \tau)$  by local linear estimator  $\hat{m}_{h_{CV}, 1}(\theta, \tau)$

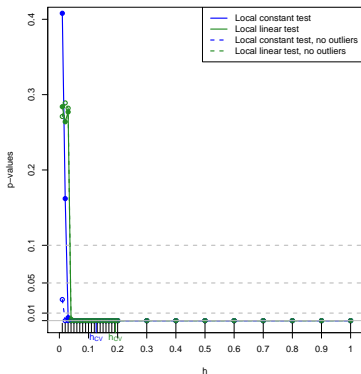


Figure: Significance trace of the goodness-of-fit tests

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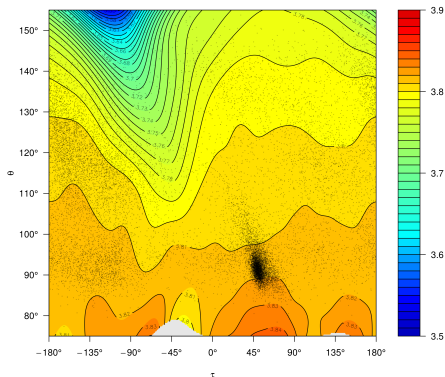


Figure: Contourplot of  $\hat{m}_{h_{CV},1}(\theta, \tau)$  and pseudo-angles sample

# Text mining application

- ▶ Data: 8121 news published in slashdot.org in 2013
- ▶ Complex data acquisition and treatment
- ▶ News:  $\mathbf{X} \in \Omega_{1508-1}$ . Log-number of comments:  $Y \in \mathbb{R}$
- ▶  $H_0 : m(\mathbf{x}) = c + \boldsymbol{\eta}^T \mathbf{x}$  such that only  $d = 77$  coefficients are non-zero.  $d$  chosen using overpenalized LASSO
- ▶ Grid of 10 bandwidths with  $B = 1000$  bootstrap replicates
- ▶ No evidence to reject the model

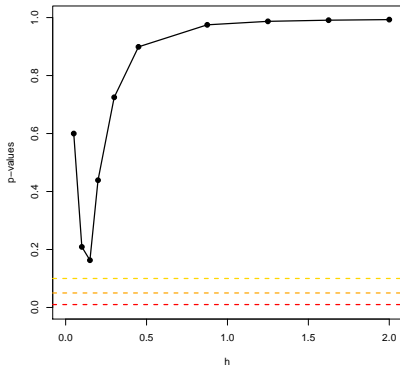


Figure: Significance trace of the goodness-of-fit test



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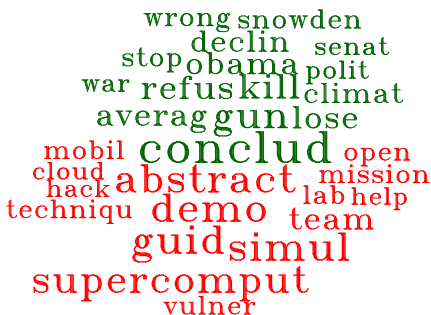


Figure: Most influential coefficients (significances of the  $d$  coefficients are  $< 0.002$ )





# Thanks for your attention!

